

From Honey Bee to Mouse Brain

Scaling neural networks beyond 80 billion parameters

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Stats 285 - Stanford

Who am I?

- Research Scientist at Google Research
 - Natural Language Understanding/Machine Translation
- PhD Thesis
 - Connectionist Multi-Sequence Modelling
 Supervisors: Dr. Fatos Yarman Vural Middle East Technical University
 Dr. Kyunghyun Cho New York University
- Research Interests
 - Sequence to sequence models: NMT
 - Multilingual Models for NLP
 - Multi-task, Continual learning, Meta-learning
 - Trainability of Neural Networks
 - Used to do some computational neuroscience



how many neurons in the brain

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About 39,600,000 results (0.58 seconds)

100 billion neurons

Neurons in the Human Brain

According to many estimates, the human brain contains around **100 billion neurons** (give or take a few billion). Jun 11, 2019

How Many Neurons Are in the Brain? - Verywell https://www.verywellmind.com/how-many-neurons-are-in-the-t



J Q

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| how many connections in the brain | | | | | | ! Q | |
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About 160,000,000 results (0.54 seconds)

Each individual neuron can form thousands of links with other neurons in this way, giving a typical **brain** well over 100 trillion synapses (up to 1,000 trillion, by some estimates). Functionally related neurons connect to each other to form neural networks (also known as neural nets or assemblies).



Neurons & Synapses - Memory & the Brain - The Human Memory www.human-memory.net/brain_neurons.html

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Unstoppable Force





Unstoppable Force vs Immovable Object





Scaling Up Neural Networks











Towards Universal Translation

- Number of Languages: 103 languages
 - \rightarrow Single Neural Network Capable of Translating between any two.
 - \rightarrow Massively Multilingual, Multi-task Setup
 - \rightarrow Open domain dataset, crawled from Web $\mathbf{25}$ billion examples
- Number of Neurons: Model Size
 - \rightarrow Orders of magnitude larger than traditional translation models (Transformer 400M)
 - \rightarrow Massive in terms of number of trainable parameters (6B 90B parameters)
 - \rightarrow Very deep and wide (1024 layers deep, 16k wide)











Outline

- **Prototyping** Engineering perspective
- **Debugging** *ML* perspective
- Hyper-parameter Search ML perspective
- **Reproducibility** Engineering perspective
- Bonus: Coordination



Machine Translation

in a nutshell



Google Translate



30 trillion

sentences translated per year

Sentence-level quality is improving



Side by Side







What is behind?

The Paradigm: Sequence to Sequence Learning

The Task: Neural Machine Translation



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Neural Machine Translation





Transformer: Attention is All You Need - Vaswani et al. 2017





Multilingual Neural Machine Translation







Develop a universal translation model (i.e,. a single model across 1000+ languages)



"Perhaps the way [of translation] is to descend, from each language, down to the common base of human communication -the real but as yet **undiscovered universal language** -- and then re-emerge by whatever particular route is convenient."

Warren Weaver (1949)





1. Massively Multilingual MT A/ Data

<u>Massively Multilingual Neural Machine Translation</u>, Aharoni et al. NAACL 2019 <u>Massively Multilingual NMT in the Wild: Findings and Challenges</u>, Arivazhagan et al. 2019

A/Data



Sketch of Power Law Learning Curves [Hestness et al. 2017]

A/Data

- Any Sequence
- Arbitrary length
- Sequence-to-Sequence

 Machine Translation
 Sentiment Analysis
 Speech Recognition
 Image Captioning

Now at Massive Amounts

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- BERT (Devlin et al. 2018): Wikipedia
- GPT-2 (Radford et al. 2019) : Reddit
- M4 (Arivazhagan et al. 2019): Entire Internet

Convert Compute into Data

- AlphaZero, OpenAl Five: Self-Play
- AlphaStar: Multi-agent

A/Data



Massively Multilingual MT - Arivazhagan et al. 2019

Large Gains on Low-Resource Languages with Multilinguality



Stats 285





2. Massive Neural Networks A/ Compute B/ Models

<u>Training Deeper Neural Machine Translation Models with Transparent Attention</u>, Bapna et al. EMNLP 2018 <u>GPipe: Efficient Training of Giant Neural Networks using Pipeline Parallelism</u>, Huang et al. NeurIPS 2019 <u>Outrageously Large Neural Networks: The Sparsely-Gated Mixture-of-Experts Layer</u>, Shazeer et al. ICLR 2017

A/Compute



Al and Compute - Damodei and Hernandez 2018

A/Compute

- Training on 1024 TPU-v3 chips
- Bfloat16 (Brain Floating Point)
- GPipe: Micro-Batch Pipeline Parallelism (Huang et al., 2019)
 - Rematerialization (gradient checkpointing)
 - Large batches (4M examples)





A/Compute - Tensor Processing Units



Cloud TPU v2 180 teraflops 64 GB High Bandwidth Memory (HBM)



Cloud TPU v3 420 teraflops 128 GB HBM



Cloud TPU v2 Pod (beta) 11.5 petaflops 4 TB HBM 2-D toroidal mesh network



Cloud TPU v3 Pod (beta) 100+ petaflops 32 TB HBM 2-D toroidal mesh network

A/Compute - BFloat16

- fp32 IEEE single-precision floating-point
- fp16 IEEE half-precision floating point
- bfloat16 16-bit brain floating point



The dynamic range of bfloat16 is greater than that of fp16.



A/Compute - Data and Model Parallelism

Loss Training on 1024 TPU-v3 chips Device 3 B₃ F₃ Bfloat16 (Brain Floating Point) GPipe: Micro-Batch Pipeline Parallelism (Huang et al., 2019) F₂ B_2 Device 2 Rematerialization 0 (gradient checkpointing) Large batches (4M examples) Ο F₁ **B**₁ Device 1 B₀ F₀ Device 0 Gradients

GPipe: Efficient Training of Giant Neural Networks using Pipeline Parallelism, Huang et al. NeurIPS 2019

Only one accelerator is active when the model is distributed across the accelerators





GPipe: Efficient Training of Giant Neural Networks using Pipeline Parallelism, Huang et al. NeurIPS 2019


More resources to ease handling large networks, painlessly (?)

- <u>Fitting larger networks into memory</u>
- <u>Reducing the Memory Usage</u>
- <u>Training Neural Nets on Larger Batches: Practical Tips for 1-GPU,</u> <u>Multi-GPU & Distributed setups</u>

B/Models



GPipe: Easy Scaling with Pipeline Parallelism - Huang et al., 2019





Aiding the Model

Aiding the Optimizer

Model enhancements to ease the training:

- Residuals
- Normalizations (layer, batch, spectral)
- Transparent Attention (Bapna et al. 2018)
- Parameter Sharing (Press and Wolf 2016, Jean et al. 2018, Dehghani et al. 2018)
- Sparsely Gated Mixture of Experts (Shazeer et al. 2017)

Step rule enhancements to ease the training:

- Sync-training
- Grad-norm tracker (Chen et al. 2018)
- Large batches
 (Goyal et al. 2017, Ott et al. 2018)
- Learning Rate Schedules (Bengio 2012)
- New step rules (Shazeer and Stern 2018, Gupta et al. 2018)
- Logit clipping
- Smart Initializations, Fixup (Zhang et al. 2019)

Putting it all together: M4









Workflow of AI Researchers working at Scale







Outline

- Prototyping
- Debugging
- Hyper-parameter Search
- Reproducibility
- Bonus: Coordination



Components of an NMT System

Training

- Reads the data, computes loss and gradients, applies parameter update.
- The most compute intensive job, runs on TPU

Inference

- Reads a checkpoint of the trained model, runs inference (beam-search)
- Generating output sequences, usually runs on GPU

Evaluation

- Reads a checkpoint of the trained model, computes loss on dev set.
- Used for monitoring the progress, usually runs on GPU or CPU







Google AI











Tensorflow Lingvo: github.com/tensorflow/lingvo





Trainer

- Construct TF training graph for a model. (cs)
 - Place variables
 - Place forward/backward computations
 - Summary
- Repeatedly calls: (TF 1.x)
 - TF session.run(train_op)

```
class TrainerTpu(base_runner.BaseRunner):
    """Trainer on TPU."""
```

```
def __init__(self, *args, **kwargs):
    super(TrainerTpu, self).__init__(*args, **kwargs)
```

self._cluster_def = self._cluster.worker_cluster_def

self._initialized = threading.Event()

tf.logging.info(

'Creating TrainerTpu using data parallelism %s '
'and %s steps_per_loop', data_parallelism, self._steps_per_loop)

https://github.com/tensorflow/lingvo/blob/master/lingvo/trainer.py

Prototyping Workflow - I

- 0. Read bunch of papers, ask a research question, hypothesize a solution
- 1. Play first in a colab (quick & dirty)
 - a. Isolated component, not even a layer (method) but a subroutine
 - b. Validate that the math works



Prototyping Workflow - II

- 0. Read bunch of papers, ask a research question, hypothesize a solution
- 1. Play first in a colab (quick & dirty)
 - a. Isolated component, not even a layer (method) but a subroutine
 - b. Validate that the math works



- 2. Write a unit test (quick & NOT dirty)
 - a. Start with some smoke tests
 - b. Then validity tests

Inherit from test_utils.TestCase.

In a test method:

• Construct the layer graph.

Inherit from test_utils.TestCase.

In a test method:

- Construct the layer graph.
- Verify:
 - The graph is constructible

def testEncoderConstruction(self):

- p = self._EncoderParams()
- _ = encoder.MTEncoderV1(p)

Inherit from test_utils.TestCase.

In a test method:

- Construct the layer graph.
- Verify:
 - The graph is constructible
 - # variables

def testEncoderVars(self): p = self._EncoderParams() mt_enc = encoder.TransformerEncoder(p) enc_vars = mt_enc.vars flatten_vars = enc_vars.Flatten() self.assertEqual(len(flatten_vars), 91)

Inherit from test_utils.TestCase.

In a test method:

- Construct the layer graph.
- Verify:
 - The graph is constructible
 - # variables
- Create inputs (tf.constant, feed_dict).
- Run the graph.

Inherit from test_utils.TestCase.

In a test method:

- Construct the layer graph.
- Verify:
 - The graph is constructible
 - \circ # variables
- Create inputs (tf.constant, feed_dict).
- Run the graph.
- Verify:
 - Shapes

```
a, m = frnn.FPropDefaultTheta(src_encs, src_paddings, inputs, paddings)
frnn_out = tf.concat([a, m], 2)
# Initialize all the variables, and then run one step.
tf.global_variables_initializer().run()
ys, = sess.run([frnn out])
self.assertEqual(ys.shape, (7, 6, 8))
```

Inherit from test_utils.TestCase.

In a test method:

- Construct the layer graph.
- Verify:
 - The graph is constructible
 - \circ # variables
- Create inputs (tf.constant, feed_dict).
- Run the graph.
- Verify:
 - Shapes
 - Output values

```
with self.session(use_gpu=True) as sess:
    tf.global_variables_initializer().run()
    actual_decode = sess.run(decode)
```

```
expected_topk_ids = [[2, 0, 0, 0, 0], [11, 2, 0, 0, 0], [2, 0, 0, 0],
[6, 2, 0, 0, 0]]
```

```
expected_topk_lens = [1, 2, 1, 2]
expected_topk_scores = [[-3.78467, -5.771077], [-3.334115, -5.597376]]
```

self.assertAllEqual(expected_topk_ids, actual_decode.topk_ids)
self.assertAllEqual(expected_topk_lens, actual_decode.topk_lens)
self.assertAllClose(expected_topk_scores, actual_decode.topk_scores)

Prototyping Workflow - III

- 0. Read bunch of papers, ask a research question, hypothesize a solution
- 1. Play first in a colab (quick & dirty)
 - a. Isolated component, not even a layer (method) but a subroutine
 - b. Validate that the math works



- 2. Write a unit test (quick & NOT dirty)
 - a. Start with some smoke tests
 - b. Then validity tests
- 3. Actual Runs
 - a. Test it locally (within a simulated environment), if passes
 - b. Run it on Data Centers with single machine, if passes
 - c. Fully fledged run using multiple machines.

Prototyping

do's

- Minimal code for the research question
- Does only one thing
- Math validated in a colab
- Written smoke tests
- Written detailed functionality tests

don'ts

- Start with the final framework
- Add multiple functionalities
 - Too much branching in the code
 - Multiple options in the signature
- Missing tests
 - No tests for varying precision
 - No functionality tests (loss decreasing)

Prototyping Massive Models: Width vs Depth (1.3B wide vs 1.3B deep)

Any \rightarrow En translation performance with model size



Prototyping Massive Models: Reducing the Problem

- Multi-source Neural Machine Translation (Zoph and Knight, 2016)
 - Need to device a merger operation (i.e. sum, avg, gate)
 - Models take too long to train
 - Too many options to try
- Reduce the problem to a chewable size
 - Perhaps down to MNIST level









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Debugging Large Scale Models

Sources of "bugs" in large scale machine learning:

- 1. Regular bugs: introduced by ML practitioner
 - a. Soln. go grab a coffee
- 2. Device/Infra bugs: hideous bugs
 - a. Soln. change device, data, data center
- 3. Theoretical bugs: well... this should've never happened in the first place
 - a. Soln. brush up your ML.
 - b. Look at the right thing, norm of the gradient vs norm of the weights.
 - c. Isolate initialization, optimization and malicious data.



Transparent Attention or Encoder -I

(Bapna et al. 2018- Training Deeper NMT Models with Transparent Attention)



Transparent Attention or Encoder -II

(Bapna et al. 2018- Training Deeper NMT Models with Transparent Attention)



Figure 1: Grad-norm ratio (r_t) vs training step (t) comparison for a 6 layer (blue) and 20 layer (red) Transformer trained on WMT 14 En \rightarrow De.

$$r_t = \left(\|\nabla_{h_1} L^{(t)}\| / \|\nabla_{h_N} L^{(t)}\| \right)$$

Indicator of a healthy training (Raghu et al. 2017)

- Lower layers converge quickly
- Topmost layers take longer

Expect large grad-norm ratio at the early stages of the training, then flatten.

Transparent Attention or Encoder -III

(Bapna et al. 2018- Training Deeper NMT Models with Transparent Attention)



Figure 3: Grad-norm ratio (r_t) vs training step for 20 layer Transformer with transparent attention.

$$r_t = \left(\|\nabla_{h_1} L^{(t)}\| / \|\nabla_{h_N} L^{(t)}\| \right)$$

Indicator of a healthy training (Raghu et al. 2017)

- Lower layers converge quickly
- Topmost layers take longer

Expect large grad-norm ratio at the early stages of the training, then flatten.


Transparent Attention or Encoder -IV

(Bapna et al. 2018- Training Deeper NMT Models with Transparent Attention)



Figure 4: Plot illustrating the variations in the learned attention weights $s_{i,6}$ for the 20 layer Transformer encoder over the training process.

| En→De WMT 14 |] | (Big) | | | |
|----------------------|-------|-------|-------|-------|-------|
| Encoder layers | 6 | 12 | 16 | 20 | 6 |
| Num. Parameters | 94M | 120M | 137M | 154M | 375M |
| Baseline | 27.26 | * | * | * | 27.94 |
| Baseline - residuals | * | 6.00 | * | * | N/A |
| Transparent | 27.52 | 27.79 | 28.04 | 27.96 | N/A |

Training dynamics:

• Raghu et al. 2017

Caveats:

• Residuals & Skip-connections \rightarrow Shallowness





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quality = $f(\mathbf{X}, \theta, \mu)$

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 All the other governing hyper-parameters

Hyper-parameter Search

First: No one has infinite resources \rightarrow the more compute we get, the larger we scale.

Some rule-of-thumbs

- All variables are interconnected: if you are changing one, expect the others to be changed
- Always start with the learning rate, then the batch-size
- Hill-climbing is as good as random search

Some tools to automate

- <u>Vizier for Cloud</u>
- Tune for Pytorch

| •• | ••• | •• | ••• | • • | • • | ••• | • • | • |
|----|-----|----|-----|-----|-----|-----|-----|---|



The Learning Rate Schedules

"Often the single most important hyper-parameter"

Practical recommendations for gradient-based training of deep architectures, Bengio 2012

Should always be tuned.

Automate via Meta-Learning

Learning the learning rate: "Online Learning Rate Adaptation with Hypergradient Descent" Baydin et al. 2017

- Apply gradient descent on the learning rate (+underlying optimizer)
- Comparison
 - Single pair (wmt'19 en-de): HG ~ Baseline
 - Multi-task (wmt en-{de,fr}): HG > Baseline
 - BERT: HG ~ Baseline



Learnt learning rate schedules (per-layer)





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Importance of Configs

For large scale experiments:

- Reproducibility is more important than code reuse, cosmetics and other conventions
- Maintaining sufficient checkpoints
- Having experimental results attached to the configs

```
@model registry.RegisterSingleTaskModel
class WmtEnDeTransformerBase(base model params.SingleTaskModelParams):
 """Params for WMT'14 En->De."""
 DATADIR = '/usr/local/google/wmt14/wpm/'
 VOCAB SIZE = 32000
 Aclassmethod
 def Train(cls):
   p = input generator.NmtInput.Params()
   p.file pattern = 'tfrecord: '+os.path.join(cls.DATADIR, 'train.tfrecords-*')
   p.tokenizer.token vocab filepath = os.path.join(cls.DATADIR, 'wpm-ende.voc')
   p.bucket batch limit = ([128, 102, 85, 73, 64, 51, 42])
   return p
 Aclassmethod
 def Dev(cls):
   p = input_generator.NmtInput.Params()
   p.file pattern = 'tfrecord:' + os.path.join(cls.DATADIR, 'dev.tfrecords')
   p.tokenizer.token vocab filepath = os.path.join(cls.DATADIR, 'wpm-ende.voc')
   p.bucket batch limit = [16] * 8 + [4] * 2
   return p
 Aclassmethod
 def Test(cls):
   p = input generator.NmtInput.Params()
   p.file pattern = 'tfrecord:' + os.path.join(cls.DATADIR, 'test.tfrecords')
   p.tokenizer.token vocab filepath = os.path.join(cls.DATADIR, 'wpm-ende.voc')
   p.bucket batch limit = [16] * 8 + [4] * 2
   return p
 Aclassmethod
 def Task(cls):
   p = base config.SetupTransformerParams(
        model.TransformerModel.Params(),
        name='wmt14 en de transformer base',
        vocab size=cls.VOCAB SIZE,
        model dim=512.
        hidden dim=2048,
        num heads=8,
        num layers=6,
        residual dropout prob=0.1,
        input dropout prob=0.1,
       learning rate=3.0,
        warmup steps=40000)
   p.eval.samples per summary = 7500
    return p
```

Bonus

Platform independent frameworks

TF -> CPU/GPU/TPU/Mobile/Browser

Don't get lost in the nuances, Ask yourself, which research question I'm trying to answer all the time There is no end in optimization

Working with larger teams Async approaches

We need something post-silicone



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"Essentially, all models are wrong, but some are useful"

George E. P. Box



Thank You

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